Ian Spehar

Engineering Portfolio

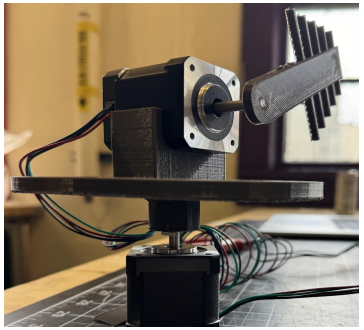
Automatic Antenna Tracker

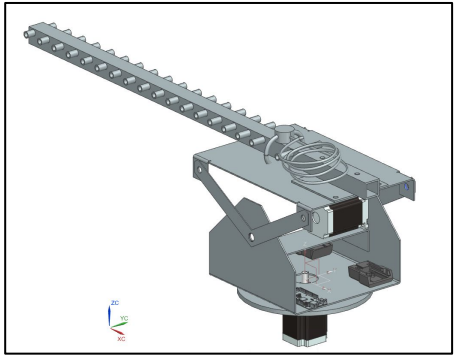
OSU Rocket Team Project

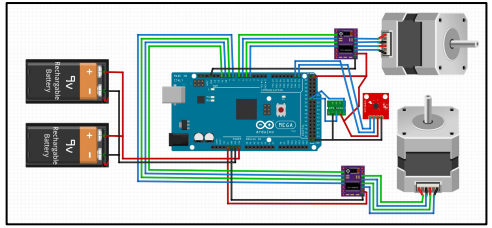
Overview: Keeps the antenna aligned for constant communication with the rocket, improving launch data collection and rocket retrieval

Personal contributions: Founded the project, developed all of the tracking logic software, and assisted with the mechanical design

Code Features: Performs real-time calculations using GPS data to keep it locked onto the rocket, actuating motors for precise tracking. It optimizes the tracking path for the quickest route and includes safety cutouts for secure operation







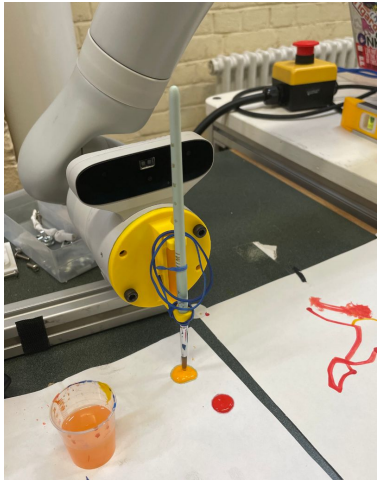
Pollock, The Painting Robot

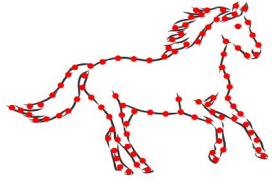
ROB-514 Project

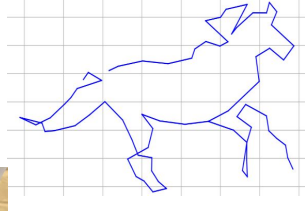
Overview: Pollock is a repurposed Kinova robot arm that autonomously analyzes images and translates them into artistic interpretations using brush strokes

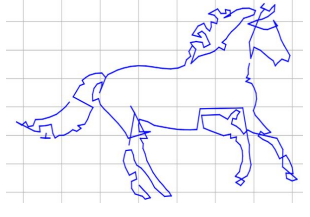
Personal contributions: Developed the core algorithm that interprets images and converts them into a sequence of brush stroke commands for the robot to follow

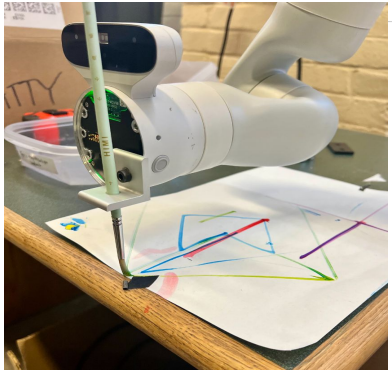
Code Features: Processes images by identifying contours and condensing them into points. Implements advanced pathing logic to create sequenced brush strokes, producing a painting resembling the original image











Robot Car

Personal Project

Overview: Remote-controlled robot car run wirelessly by PS4 controller featuring collision avoidance, precision servo steering, and voice responses

Personal contributions: Developed all software, designed and assembled the electrical circuit, and built the body and steering mechanism using Legos and duct tape

Code Features: Includes automated controller pairing and startup, crash deterrence, and will insult you in a British accent when you almost crash